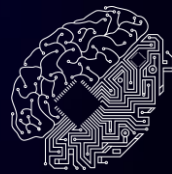


MAKING  
ROBOTS  
UNDERSTAND  
HUMANS



ROBOTAI



## ABOUT ROBOTAI

- Established in 2018, Israel.
- Funded and supported by Israeli Innovation Authority, Hamlet, Haifa and Private investors
- Develops 3D Vision for robotics and automation
- [www.robotai.info](http://www.robotai.info)

## THE MANUFACTURING IS STILL LABOR INTENSIVE. WHY?

- Complicated actions
- Dynamic environment
- Human “eye” understanding
- Coordination
- High cost



# THE PROBLEM | Many tasks require situation awareness

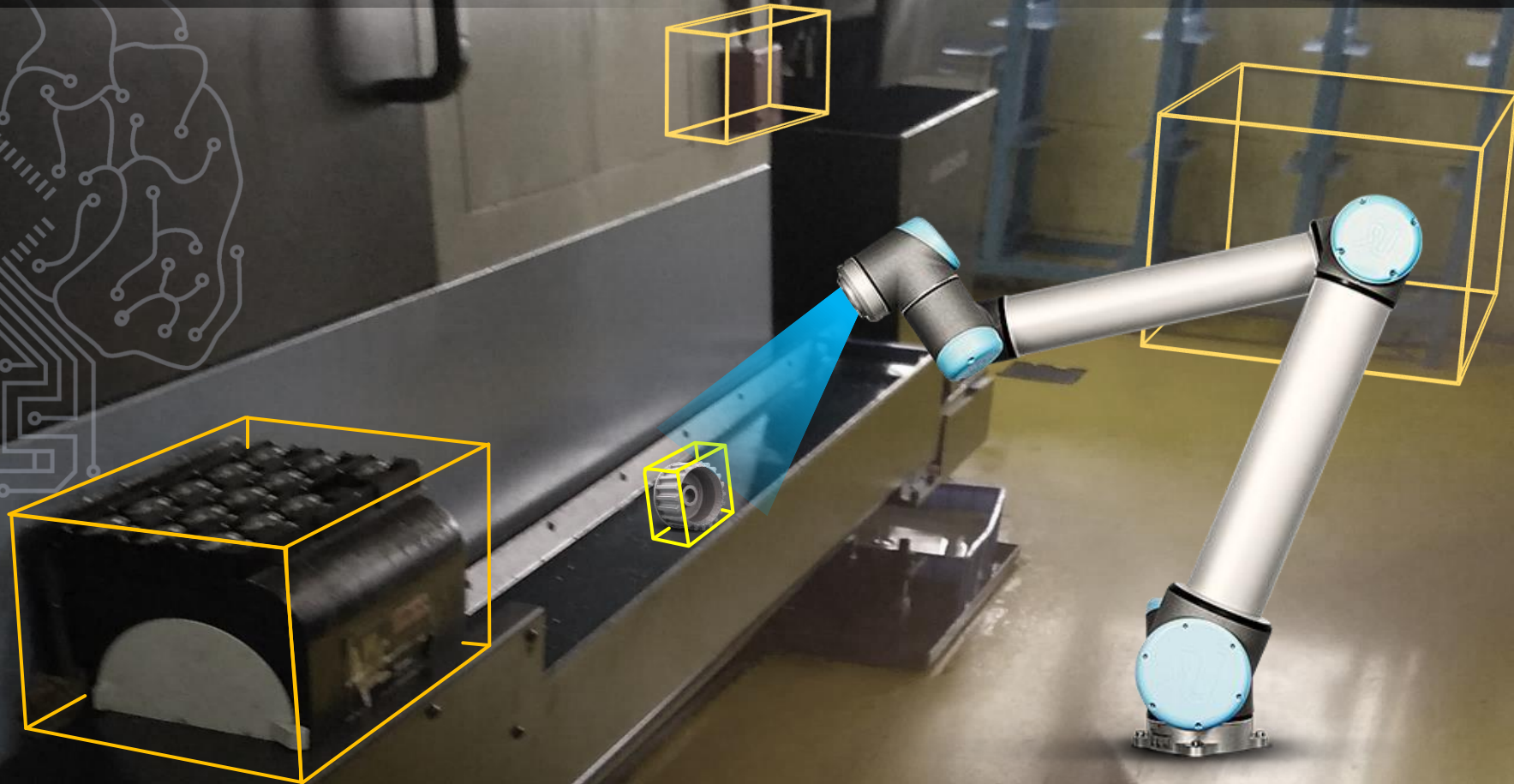
Robots must see and adapt to the changing environment



# ROBOTS CAN NOT BE BLIND | 3D Object Awareness

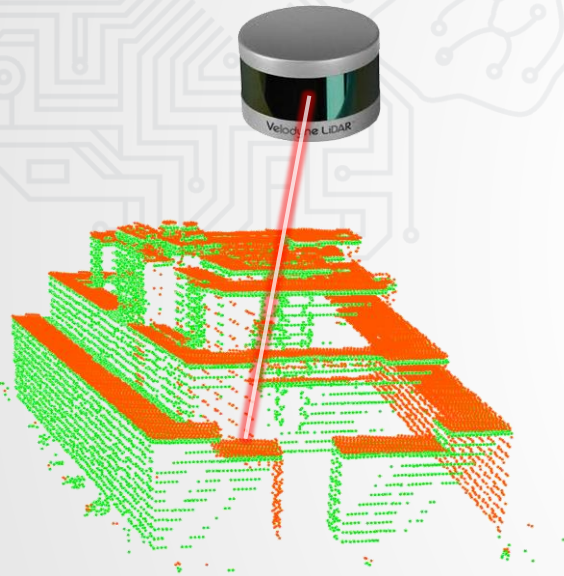


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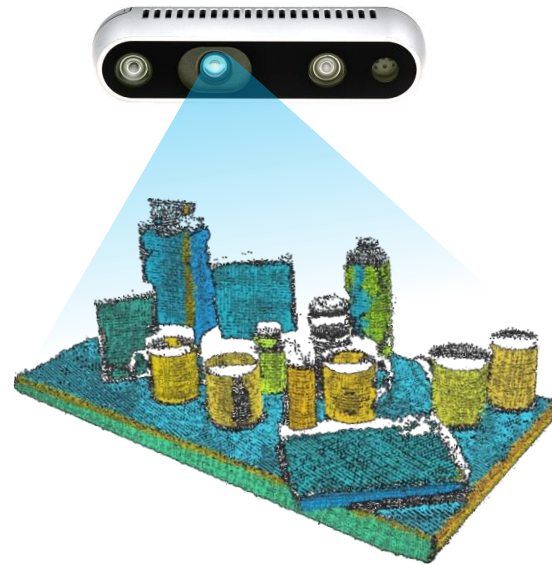


Most robots today are blind therefore limited, robots **MUST SEE** and understand **OBJECTS** like humans

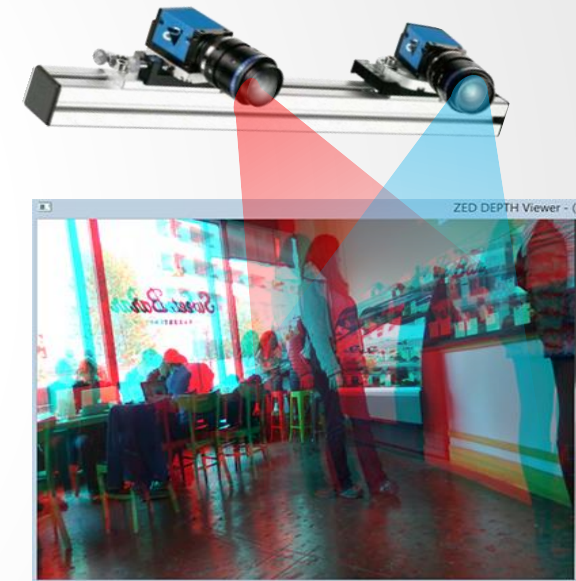
3D vision sensors that compute depth



LIDARS



STRUCTURAL LIGHT



MULTIPLE CAMERAS

DRAWBACKS : non-flexible, complex setup, limited object types

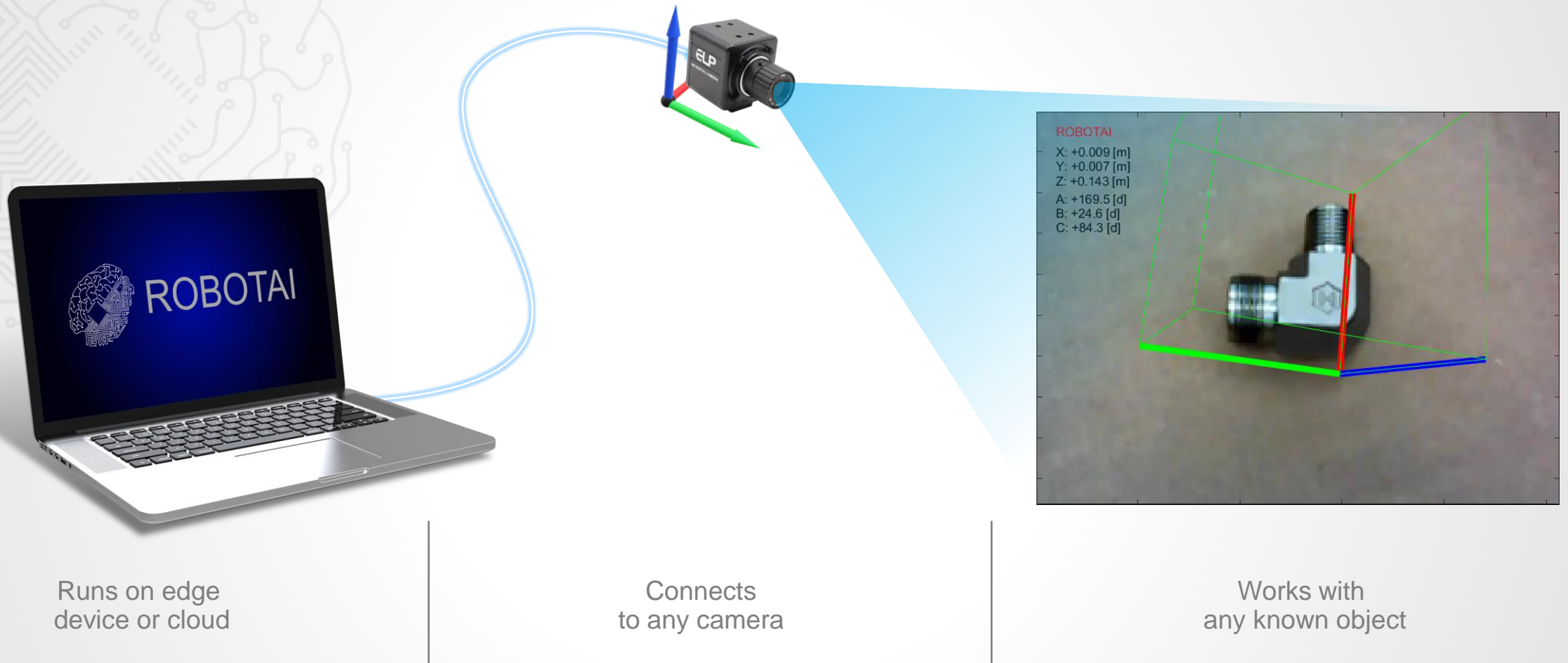
# OBSERVATION : We do not need 2 eyes



We can see in 3D using one eye only



# OUR IP : Software that transforms any camera into a 3D vision device

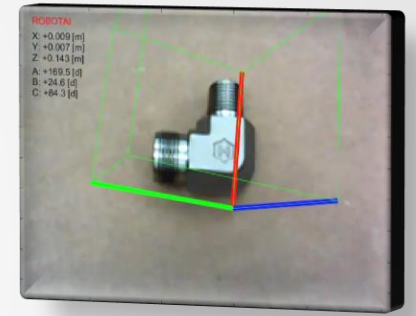
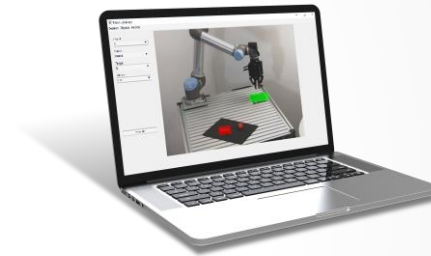
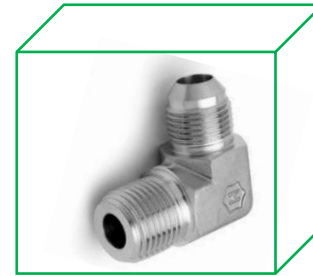


AI based software, can recognize and localize **any known object** using a single 2D camera



# HOW IT WORKS

We can teach machine to recognize any object, along with its position



Object image  
data



**LABEL6D**

Training  
software



Object  
models



**POSE6D**

Edge  
software



Object  
pose

BENEFITS: fast setup, no coding, no special scanning, no CAD data, adjustable to any object

# OUR ADVANTAGES : Simplicity and Versatility



ROBOTAI

## KEY DIFFERENTIATION:

- ▶ Camera and Robot Agnostic
- ▶ Detects Any Known Object
- ▶ Software Only Solution
- ▶ Fast – 30 frame/sec
- ▶ Precision – 0.5 mm
- ▶ Flexible



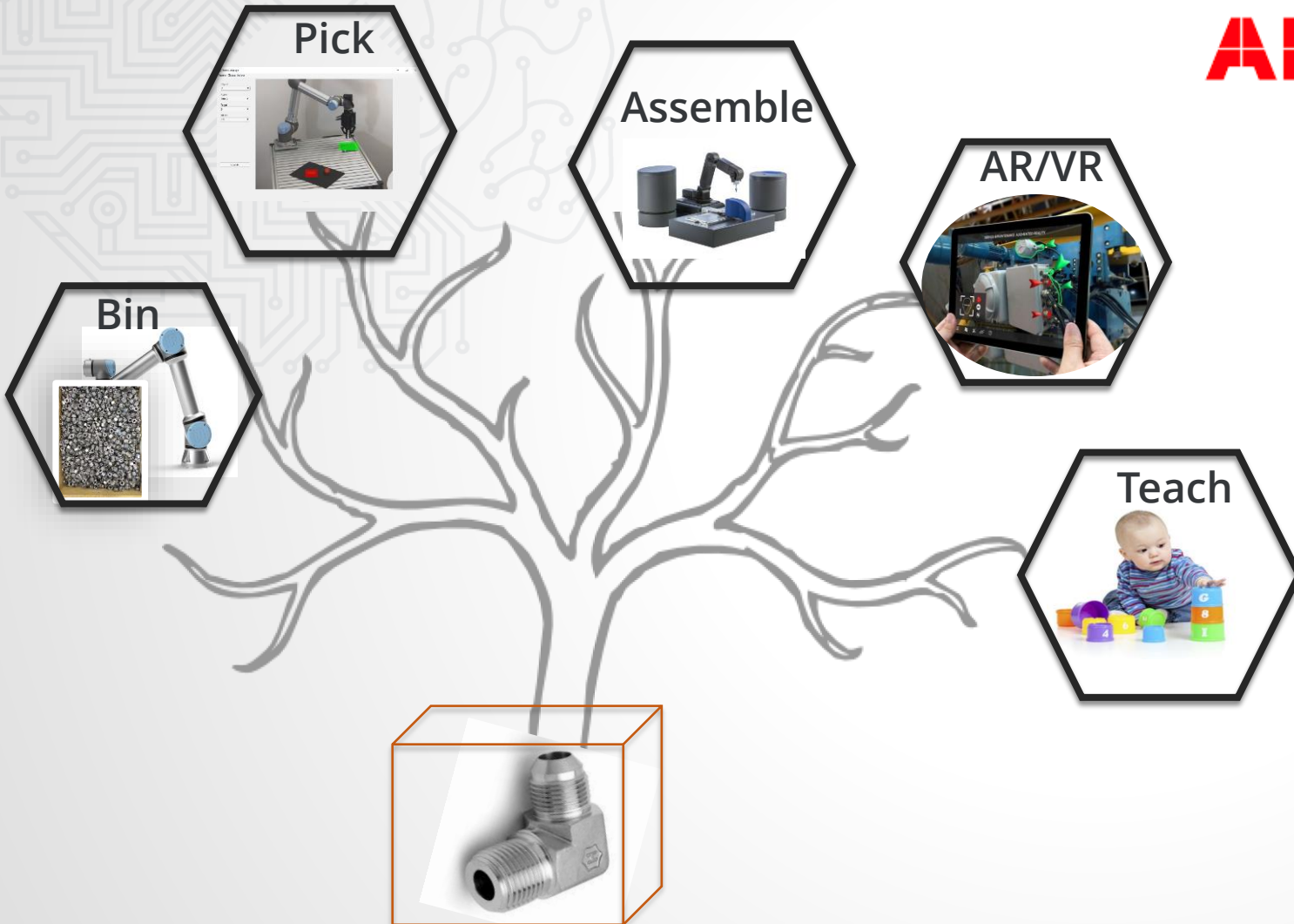
# COMPETITIVE ANALYSIS

## Sensor Type

	Canon <sup>1</sup>	Osaro <sup>2</sup>	Mech-Mind <sup>3</sup>	Solomon <sup>4</sup>	RobotAI
					
Precision [mm]	+/-2.0	+/-5.0	+/-0.5	+/-1.0	+/-0.3
Scan Time [sec]	1.8	0.5	0.3-0.9	0.5	0.05
Solution Prices [\$]	35K	60K	15K	22.5K	3K-10K
Object Types	Specific	Some	Specific	Some	All
System Setup	Fast	Slow	Fast	Fast	Slow

\*SELECTED COMPETITORS

# MAIN APPLICATIONS & TRACTION





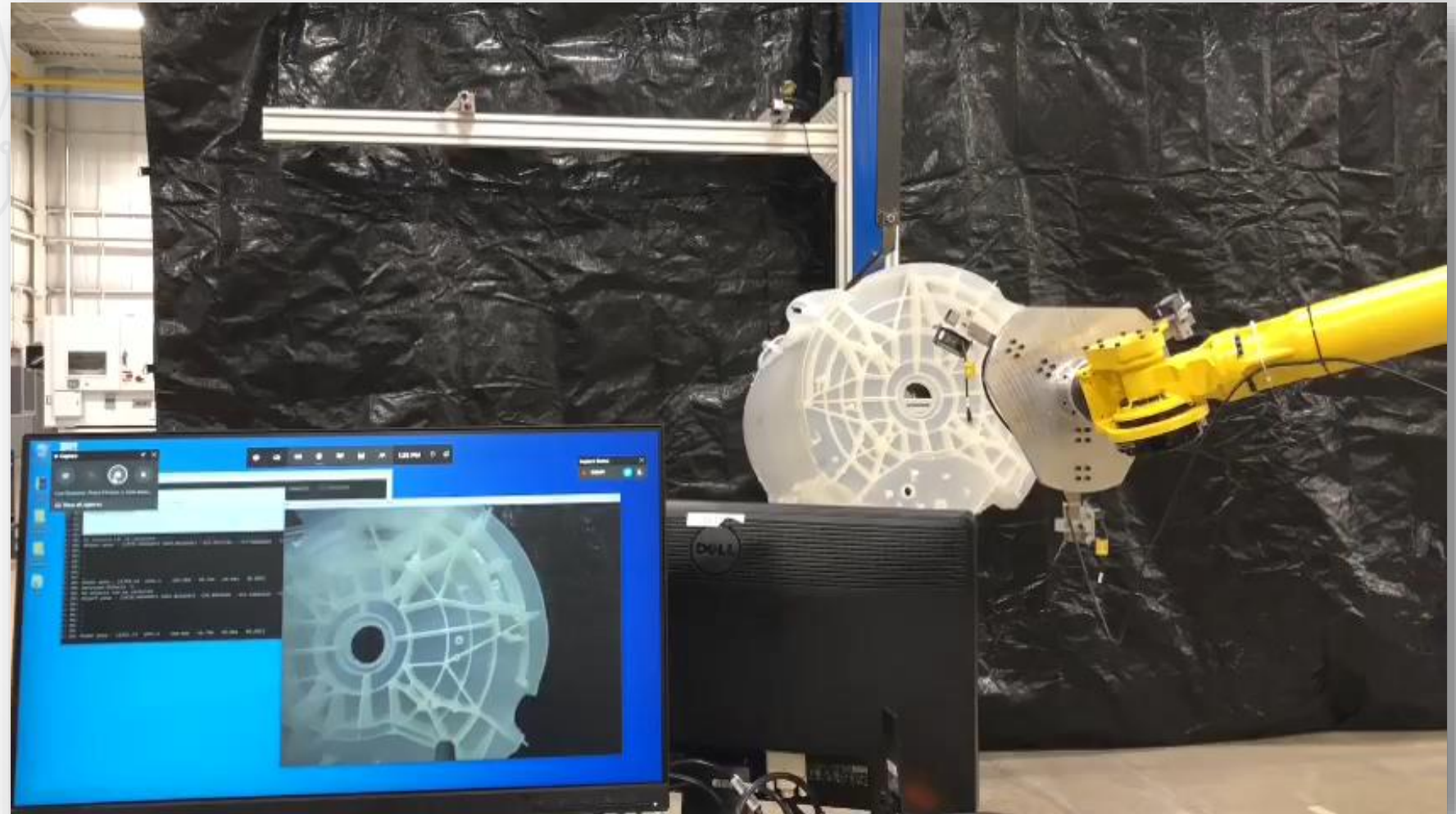
# USE CASES

# USE CASE: Fast Moving Objects



## KEY BENEFITS:

- ▶ Fast
- ▶ Flexible
- ▶ Complex parts
- ▶ Fast setup
- ▶ Conveyor motion
- ▶ Productivity



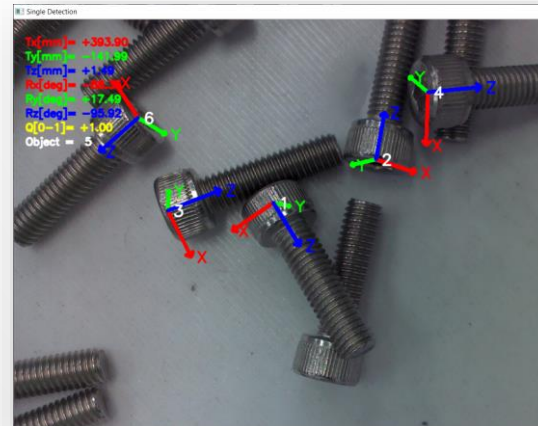
[link](#)

# USE CASE: Precision – Bin Picking



## KEY BENEFITS:

- ▶ Fast
- ▶ Flexible
- ▶ Different Parts
- ▶ Fast Setup
- ▶ Cost Effective
- ▶ Productivity



[link](#)

# USE CASE : Packages and Textures - Logistics

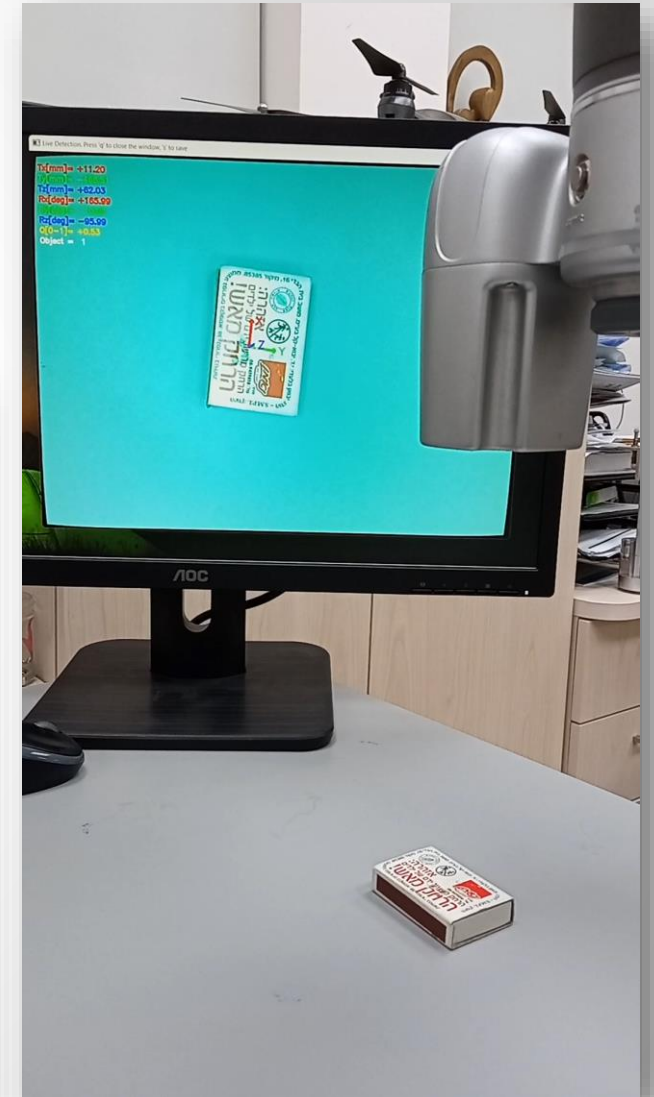


## KEY BENEFITS:

- ▶ Textures and Pictures
- ▶ Flexibility
- ▶ Fast tracking
- ▶ Robot guidance



[link](#)



[link](#)

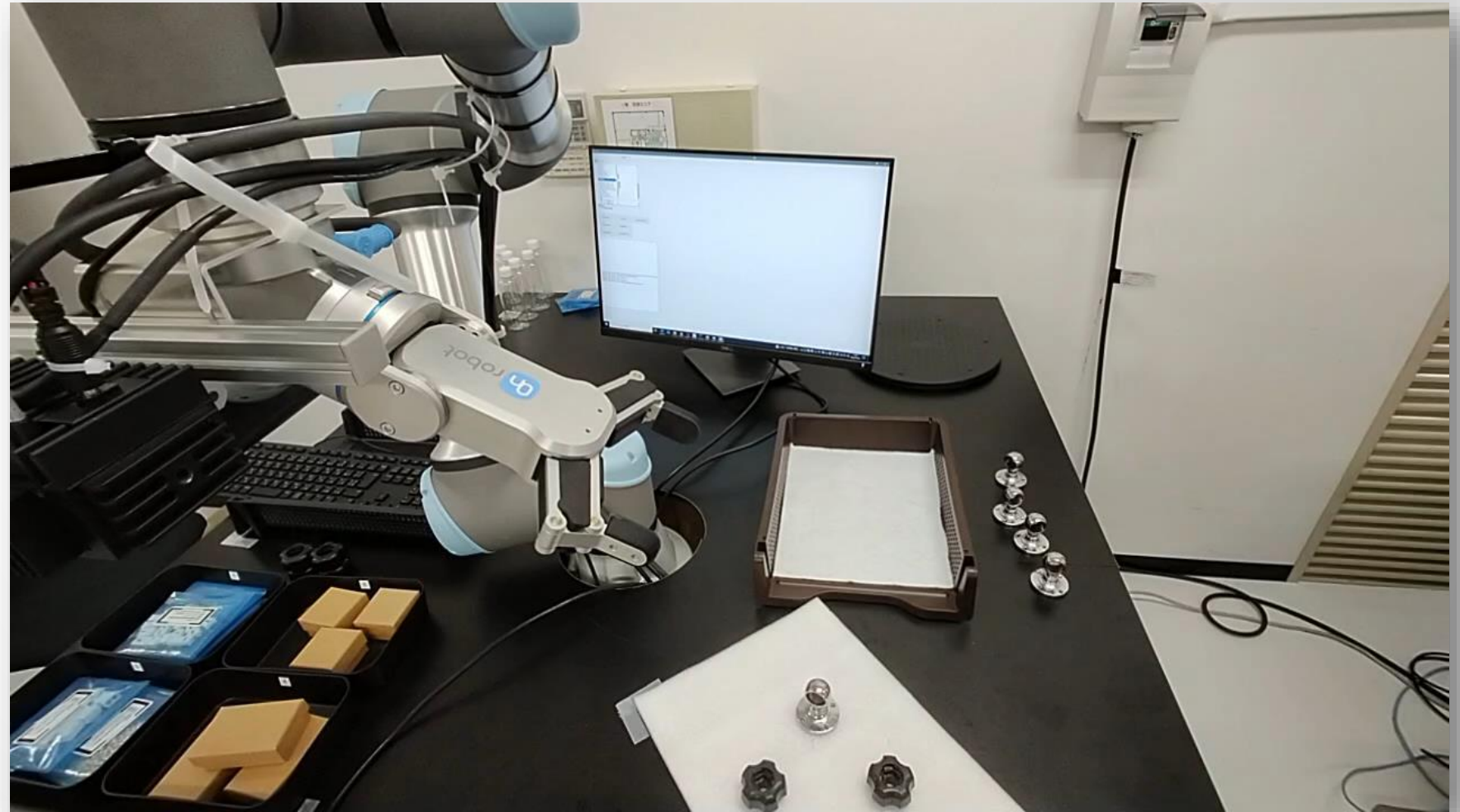


# USE CASE : Multiple Objects Handling



## KEY BENEFITS:

- ▶ Fast
- ▶ Short cycle time
- ▶ Simple sensor
- ▶ Fast setup
- ▶ Easy to deploy
- ▶ Multiple Objects



# USE CASE : Activity Monitoring



## KEY BENEFITS:

- ▶ Fast
- ▶ Short cycle time
- ▶ Simple sensor
- ▶ Simple setup



# USE CASE: Hand Eye Coordination For Robots - Agriculture



## KEY BENEFITS:

- ▶ Fast
- ▶ Flexible
- ▶ Cost effective
- ▶ Fast setup
- ▶ Easy to deploy
- ▶ Productivity



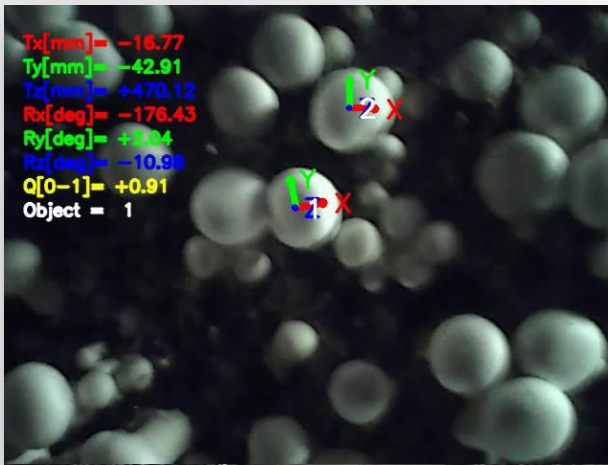
[link](#)

# USE CASE : Agriculture



## KEY BENEFITS:

- ▶ Monitoring
- ▶ Flexible
- ▶ Cost effective
- ▶ Human shortage

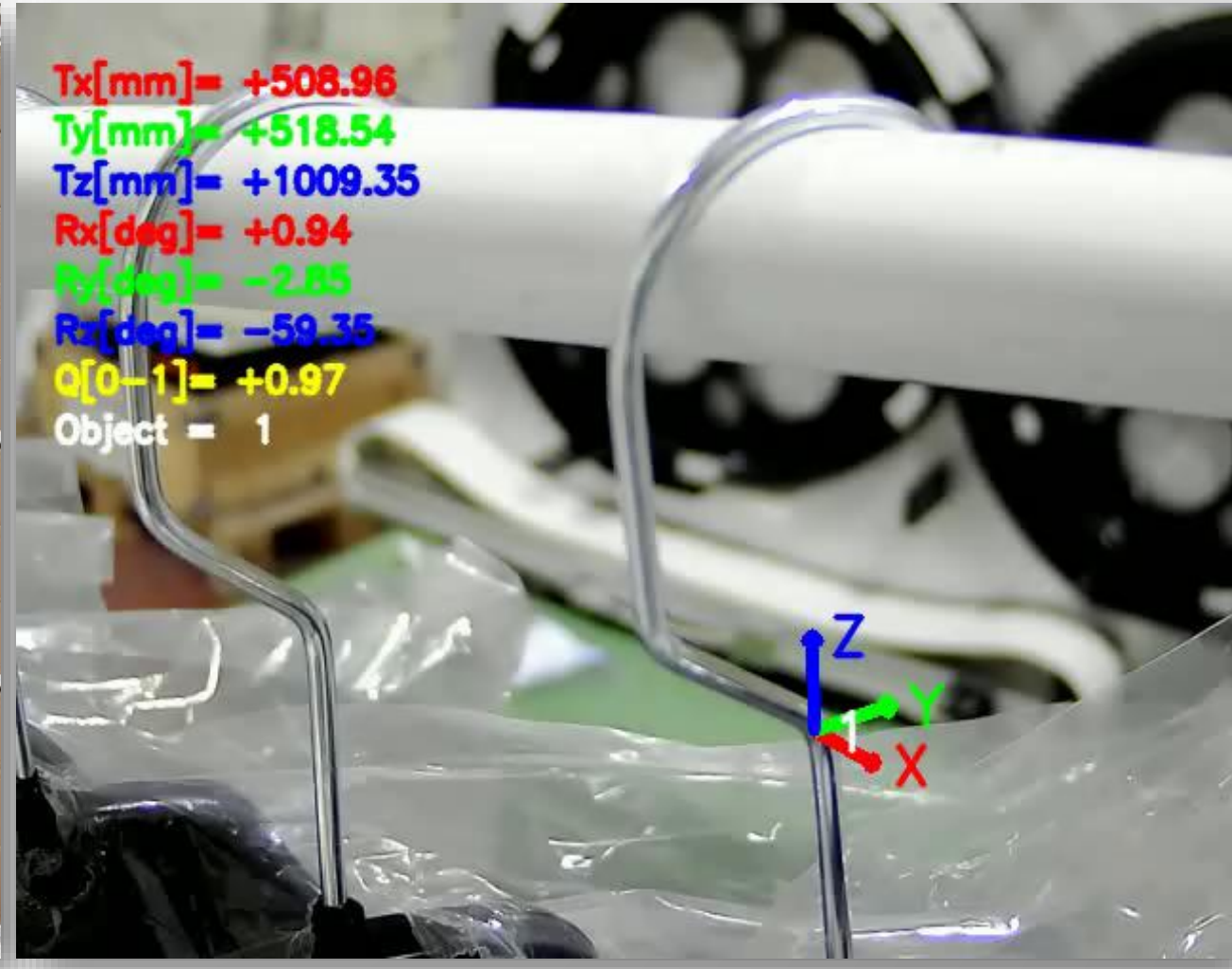


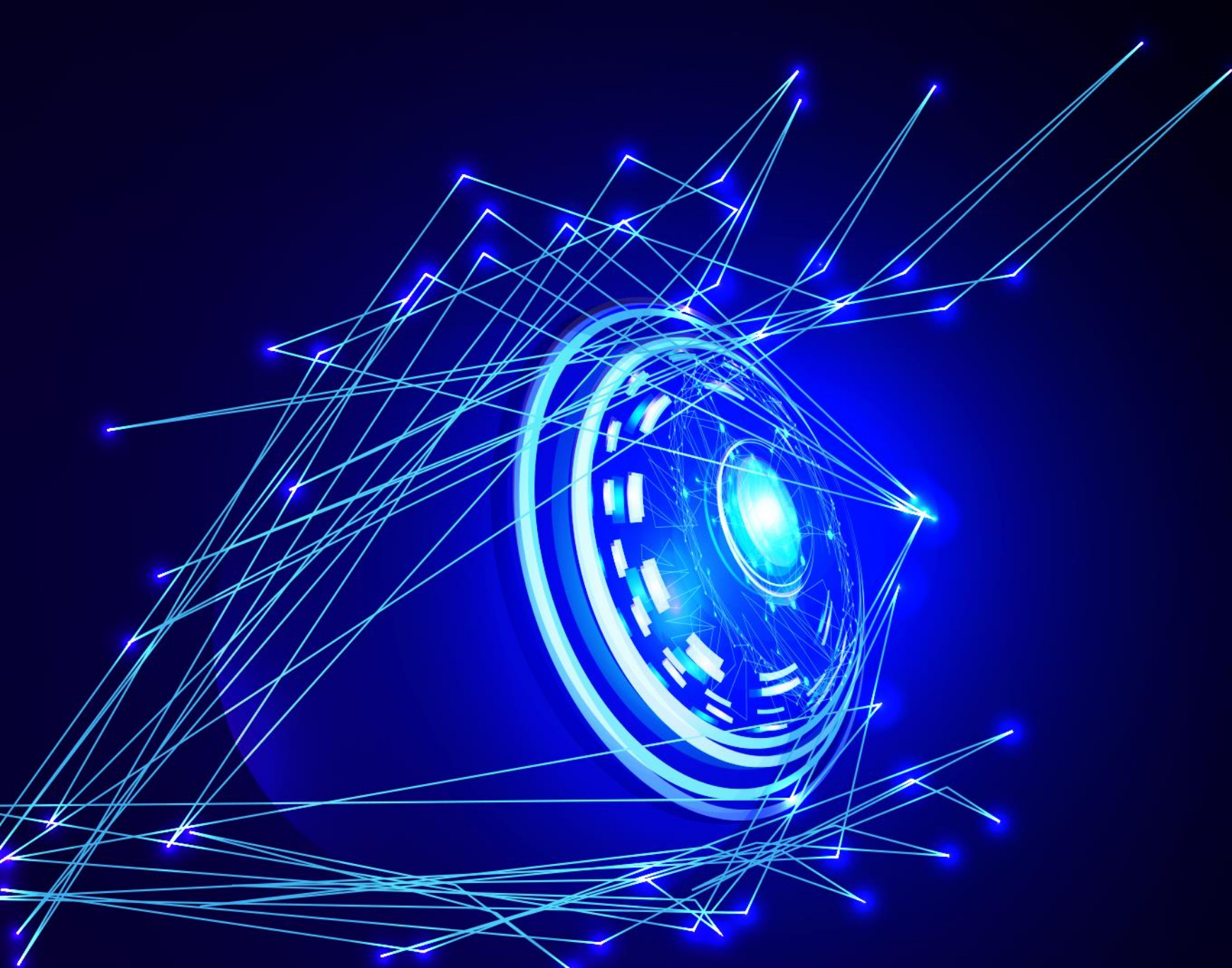
# USE CASE : Logistics Picking



## KEY BENEFITS:

- ▶ Specific Objects
- ▶ Flexible
- ▶ Cost effective
- ▶ Human shortage





THANK  
YOU



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